

Midterm 1 - Math 217

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Name: _____

Show work for all of your answers. Cross out any work that you do not want graded. **Be sure to read problem statements carefully.**

Problem	Grade	Max
1		15
2		20
3		15
4		20
5		15
6		15
Total		100

(1) Find a set of vectors in \mathbb{R}^4 which spans the solution set of the equation

$$2x_1 - x_2 + 4x_3 + 2x_4 = 0.$$

(2) (a) Find the inverse of the matrix

$$\begin{bmatrix} -1 & 1 & 1 \\ 1 & -1 & 1 \\ -1 & 2 & 1 \end{bmatrix}.$$

(b) Solve the following equation:

$$\begin{bmatrix} -1 & 1 & 1 \\ 1 & -1 & 1 \\ -1 & 2 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}.$$

- (3) Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a map which rotates points in \mathbb{R}^2 counterclockwise around the origin by an angle of $3\pi/4$. Is f a linear transformation? If not, explain why not. If so, write down the standard matrix for f .

- (4) Draw the solution set for the following linear system. Indicate the coordinates of two points in the solution set.

$$3x_1 - x_2 = 5$$

$$9x_1 - 3x_2 = 15$$

(5) Let $T: \mathbb{R}^4 \rightarrow \mathbb{R}^4$ be the linear transformation defined by

$$T(\mathbf{e}_1) = \mathbf{e}_1 + \mathbf{e}_2$$

$$T(\mathbf{e}_2) = \mathbf{e}_2 + \mathbf{e}_3$$

$$T(\mathbf{e}_3) = \mathbf{e}_3 + \mathbf{e}_4$$

$$T(\mathbf{e}_4) = \mathbf{e}_4 + \mathbf{e}_1.$$

Is T invertible? If not, explain why not. If so, write down a linear transformation that is an inverse to T .

(In this problem, $\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3$ and \mathbf{e}_4 denote the column vectors of the 4×4 identity matrix.)

(6) Indicate whether the following assertions are true or false. If an assertion is true, explain why. If an assertion is false, give a counterexample.

- Let A and B be matrices such that the matrix product AB is defined. If the matrix transformations $\mathbf{x} \mapsto A\mathbf{x}$ and $\mathbf{x} \mapsto B\mathbf{x}$ are both one-to-one, then the matrix transformation $\mathbf{x} \mapsto AB\mathbf{x}$ must be one-to-one.

- If \mathbf{b} is a vector in \mathbb{R}^m , and C is an $m \times n$ matrix that has a pivot position in every column, then the equation $C\mathbf{x} = \mathbf{b}$ must have a solution.

- (6) (cont.) • Let D be a 3×3 matrix. Then there must exist some sequence of real numbers a_0, a_1, \dots, a_n , not all zero, such that

$$a_n D^n + a_{n-1} D^{n-1} + \dots + a_1 D + a_0 I_3 = 0.$$